

Autoencoder

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Dimension Reduction

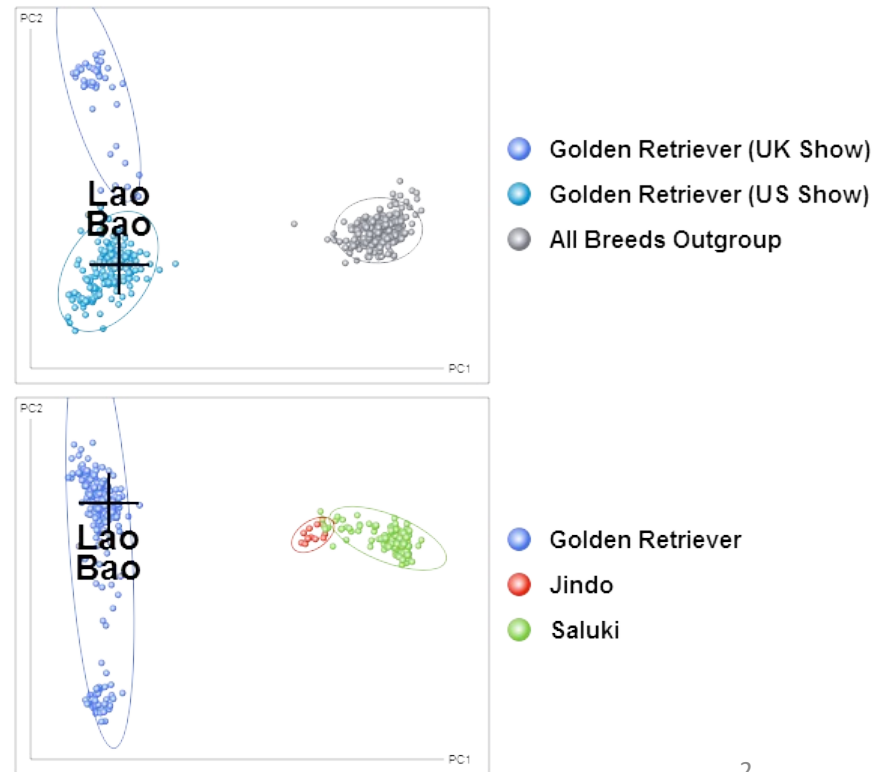
- Principle Component Analysis (PCA)
 - Projecting the data into a new space using **linear transformation**
 - Using **SVD** or **eigenvalue decomposition** to find the new space



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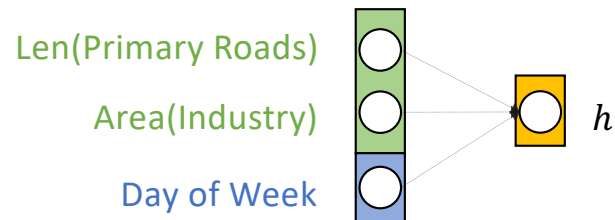
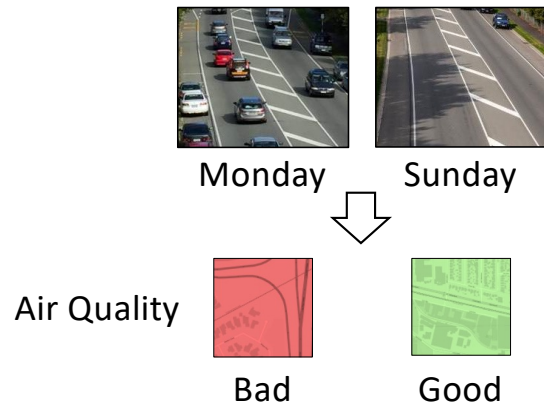
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AACCACCCCGGGGAACCTTTTGGGGTTGGAGCCTTAGAATGAGTCTTTAAGGTTCCGGTTA
GAGCGTGAAACAGAATCTGCCGGTCTCAAAAAAGGTGCGTCTCCCGGTCAGGGAAGGCCNNC
CTCCGAGTCAGAGCCACNNTTTCAGACACTTAGCCCCAGAGGGAATTTGCCTTTTAGT
ATTGGCCAAAGTCAGGGGAGCGAGTCNNAGGGTTGGAGAAGGACAAGGCCCTTC
GAGCCCGGAATTACAAAGTCAGAGTAAGTTAAAGAGTCTCTCGGTCTCTCGGTTAGC
AGCCAAAGAGGGTCGGCCGGTTGGGGAATTTGGGGCCAGAAAGTCTTGGTTAGAGAGT
GCCGGGGTTCCCCAGTCAATCTCTCTTTCTTAGGGTTCTCAATACGGAGCCAAAAAC
GATCCAAGGAACCGGCCGGCCAAGGCCGGAATTTGGAGCCGGAGAGAGCCGGAAAAG
GGGGTTAGAGAGGGTCGGAAAATCAGAAAATTTCCCTTTAAGGTTCTGTCCCTTGG
TTNNAATCGGTCAGTTGGCCTCGGGGGTTTTAACAAAAAAGTGAGGGAGAAAACA
BGTCCGAGCGAGAGCCAACCTGAGAGTTCCAATTAGCCNNGGAACCAACCAA
    
```

DNA Sequence



Linear VS. Non-Linear

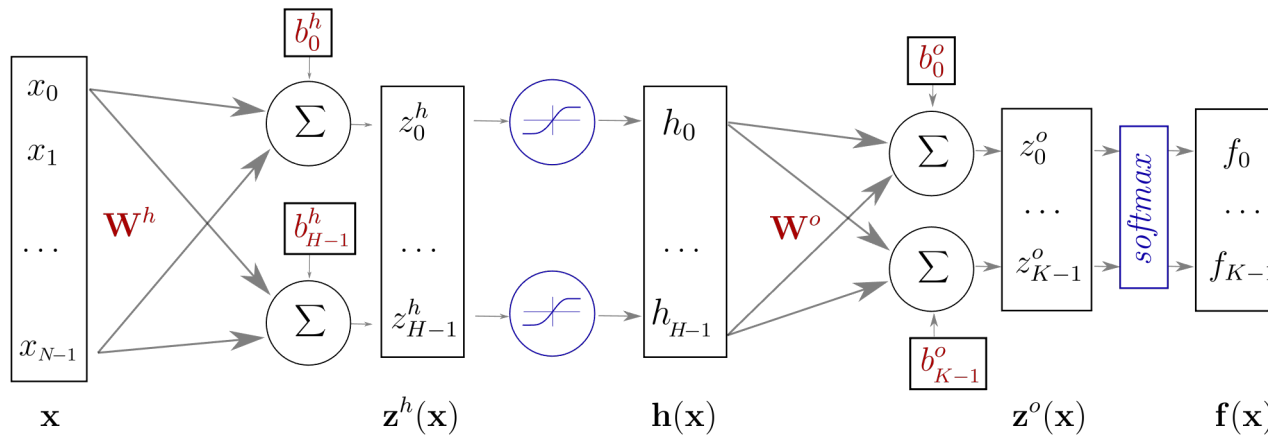
- What if the underlying low dimensional structure is not linear?
 - PCA would not be able to find good representative basis vectors
- For example,



h can be a non-linear combination of three features

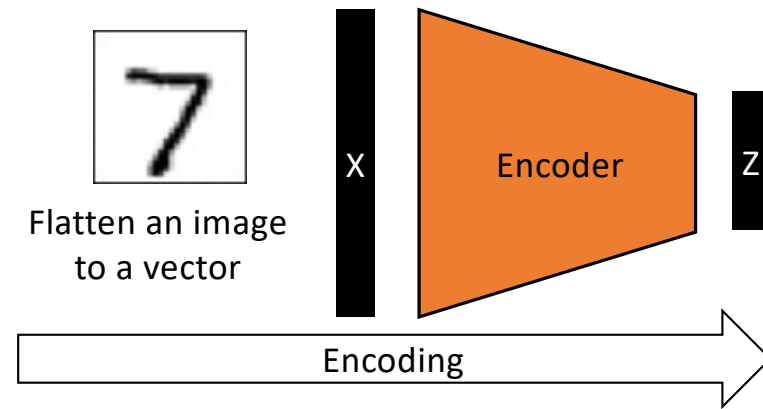
Linear VS. Non-Linear

- What if the underlying low dimensional structure is not linear?
 - PCA would not be able to find good representative basis vectors
- Neural Networks?



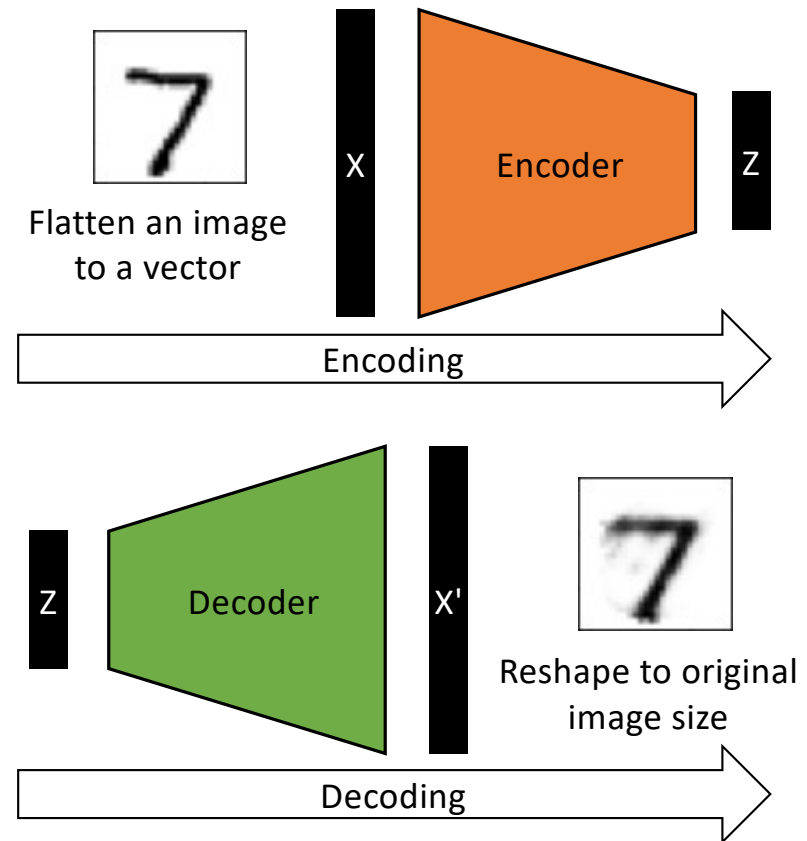
Autoencoder – Encoder and Decoder

- Encoder
 - Encoding the input X into a hidden representation Z



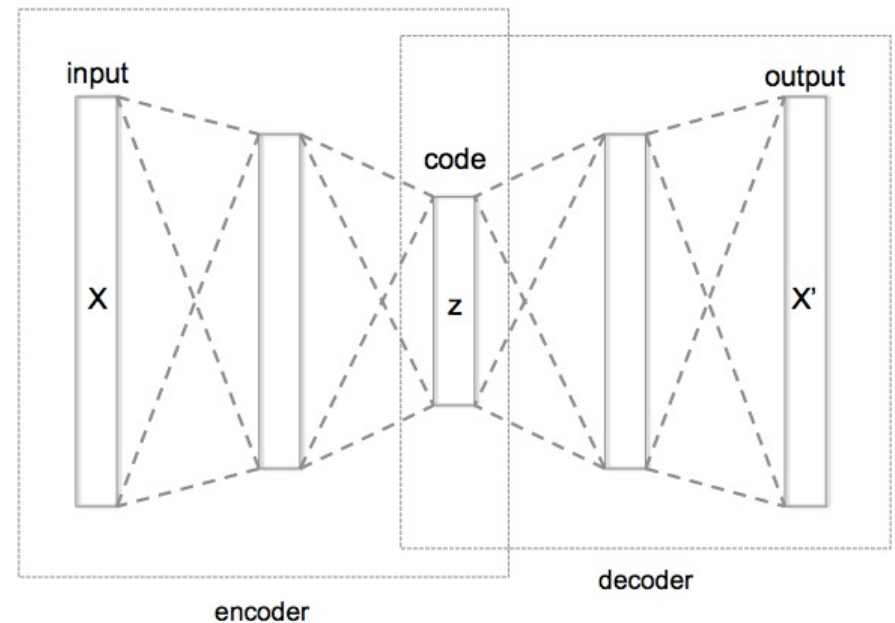
Autoencoder – Encoder and Decoder

- Encoder
 - Encoding the input X into a hidden representation Z
- Decoder
 - Decoding the input X' from the hidden representation Z



Autoencoder – Encoder and Decoder

- Encoder
 - Encoding the input X into a hidden representation Z
- Decoder
 - Decoding the input X' from the hidden representation Z
- Usually, $\text{Dim}(Z) < \text{Dim}(X)$, also called undercomplete AE



Autoencoder – Encoder and Decoder

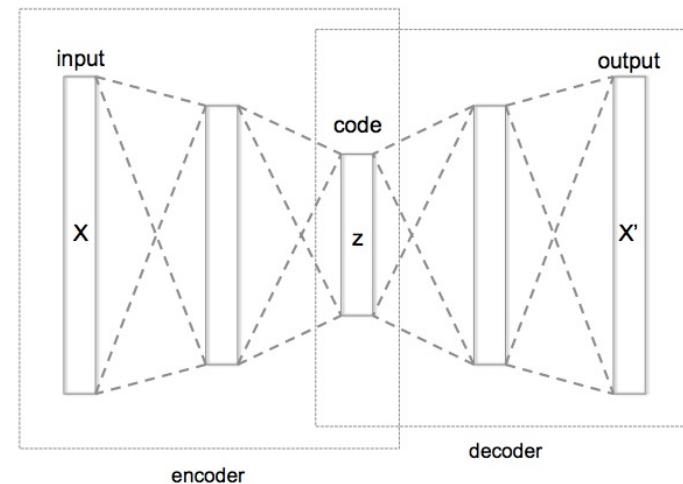
- Encoder
 - $Z = f(X) = \sigma(WX + b)$
- Decoder
 - $X' = g(Z) = \sigma'(W'Z + b')$
- σ and σ' are activation functions
- σ' depends on the input type
 - e.g., if the inputs have values between 0 and 1, we can use a Sigmoid function

For example:

W 32x64; X 64x1,000;

Z 32x1,000;

W' 64x32; X' 64x1,000



Autoencoder – Objective Function

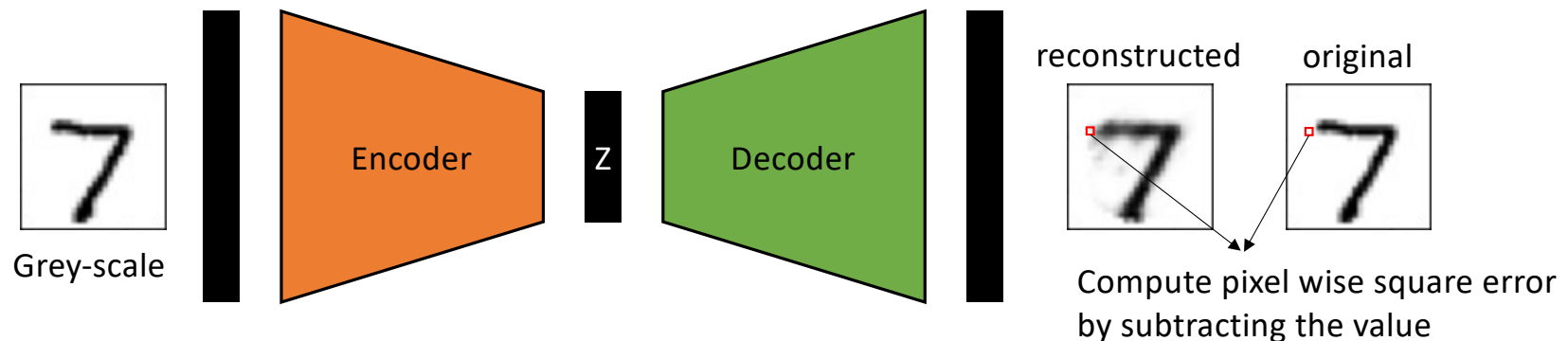
- $X' = f(g(X))$
- The model is trained to minimize a certain loss function which will ensure that X' is close to X
- Loss function depends on the inputs

Autoencoder – Objective Function

- When the inputs are real values, we can use Mean Square Error (MSE) as the loss function

$$\min_{W, W', b, b'} \frac{1}{mn} \sum_{i=1}^m \sum_{j=1}^n (x'_{ij} - x_{ij})^2$$

where m is the number of samples, and n is the number of features

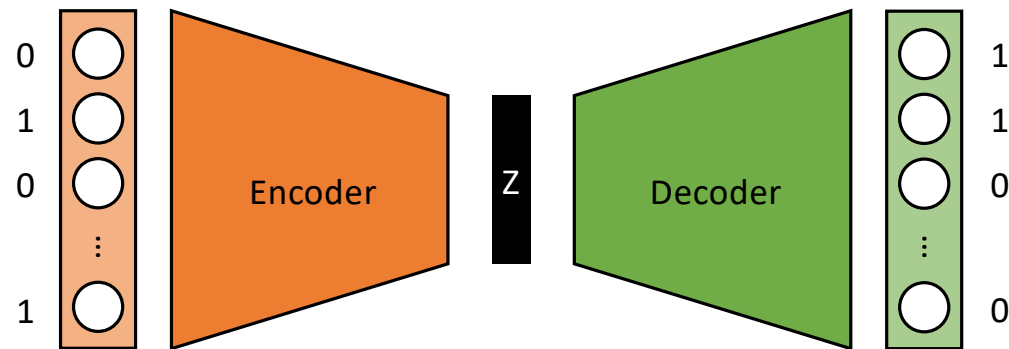


Autoencoder – Objective Function

- When the inputs are binary, we can use Binary Cross Entropy (BCE) as the loss function

$$\min_{W, W', b, b'} \frac{1}{mn} \sum_{i=1}^m \sum_{j=1}^n -(x_{ij} \log x'_{ij} + (1 - x_{ij}) \log(1 - x'_{ij}))$$

where m is the number of samples, and n is the number of features



Link Between PCA and Autoencoder

- The encoder part of an autoencoder is equivalent to PCA if
 - the encoder is a one-layer linear transformation, no bias term
 - the decoder is a one-layer linear transformation, no bias term
 - using the squared error loss function
 - normalizing the input to 0 mean along each dimension
 - also divide each input element by the square root of m
 - so that $\tilde{X}^T \tilde{X}$ is the covariance matrix of the 0 mean data

$$\tilde{x}_{ij} = \frac{1}{\sqrt{m}} \left(x_{ij} - \frac{1}{m} \sum_{k=1}^m x_{kj} \right)$$

$$\text{corr}(\mathbf{X}) = \begin{bmatrix} 1 & \frac{E[(X_1-\mu_1)(X_2-\mu_2)]}{\sigma(X_1)\sigma(X_2)} & \dots & \frac{E[(X_1-\mu_1)(X_n-\mu_n)]}{\sigma(X_1)\sigma(X_n)} \\ \frac{E[(X_2-\mu_2)(X_1-\mu_1)]}{\sigma(X_2)\sigma(X_1)} & 1 & \dots & \frac{E[(X_2-\mu_2)(X_n-\mu_n)]}{\sigma(X_2)\sigma(X_n)} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{E[(X_n-\mu_n)(X_1-\mu_1)]}{\sigma(X_n)\sigma(X_1)} & \frac{E[(X_n-\mu_n)(X_2-\mu_2)]}{\sigma(X_n)\sigma(X_2)} & \dots & 1 \end{bmatrix}$$

where x_i is the input, j is the feature dimension, and m is the number of samples

Link Between PCA and Autoencoder

- We will show that if
 - using a **linear decoder** and a **squared error loss function**
 - **the optimal solution** to the following objective function is obtained when using a linear encoder

$$\min_{W, W', b, b'} \frac{1}{mn} \sum_{i=1}^m \sum_{j=1}^n (x'_{ij} - \tilde{x}_{ij})^2$$

- The above objective function is equivalent to

$$\min(\|\tilde{X} - ZW'\|_F)^2$$

where $\|A\|_F$ is the Frobenius Norm of matrix A , $\|A\|_F \equiv \sqrt{\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2}$

Link Between PCA and Autoencoder

- The optimal solution to the problem

$$\min(\|\tilde{X} - ZW'\|_F)^2$$

is given by

$$\tilde{X} = ZW' = U\Sigma V^T \text{ Recall: from SVD}$$

where U and V are orthogonal matrices and Σ is a diagonal matrix with non-negative values on diagonal

orthogonal
matrices:

$$(V^T V = I)$$

$$(V^T = V^{-1})$$

- By matching variables one possible solution is

$$\begin{aligned} Z &= U\Sigma \\ W' &= V^T \end{aligned}$$

Link Between PCA and Autoencoder

- We will now show that Z is a linear encoding and find an expression for the encoder weight W

$$1 \quad Z = U\Sigma$$

2

3

4

5

6

Link Between PCA and Autoencoder

- We will now show that Z is a linear encoding and find an expression for the encoder weight W

$$1 \quad Z = U\Sigma$$

$$2 \quad Z = (\tilde{X}\tilde{X}^T)(\tilde{X}\tilde{X}^T)^{-1}U\Sigma$$

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$$3 \quad Z = (\tilde{X}V\Sigma^T U^T)(U\Sigma V^T V\Sigma^T U^T)^{-1}U\Sigma \quad \tilde{X} = ZW' = U\Sigma V^T$$

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$$4 \quad Z = \tilde{X}V\Sigma^T U^T (U\Sigma\Sigma^T U^T)^{-1}U\Sigma \quad (V^T V = I)$$

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$$5 \quad Z = \tilde{X}V\Sigma^T U^T U(\Sigma\Sigma^T)^{-1}U^T U\Sigma \quad ((ABC)^{-1} = C^{-1}B^{-1}A^{-1})$$

$$6 \quad \quad \quad (U^T = U^{-1})$$

Link Between PCA and Autoencoder

- We will now show that Z is a linear encoding and find an expression for the encoder weight W

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Link Between PCA and Autoencoder

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$$6 \quad Z = \tilde{X}V\Sigma^T (\Sigma^T)^{-1}(\Sigma)^{-1}\Sigma = \tilde{X}V \quad (U^T = U^{-1})$$

Link Between PCA and Autoencoder

- We will now show that Z is a linear encoding and find an expression for the encoder weight W

$$Z = U\Sigma$$

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$$Z = (\tilde{X}V\Sigma^T U^T)(U\Sigma V^T V\Sigma^T U^T)^{-1}U\Sigma \quad \tilde{X} = ZW' = U\Sigma V^T$$

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$$Z = \tilde{X}V\Sigma^T (\Sigma^T)^{-1}(\Sigma)^{-1}\Sigma = \tilde{X}V \quad (U^T = U^{-1})$$

- Thus, Z is a linear transformation of \tilde{X} and $W = V$

Link Between PCA and Autoencoder

- We have encoder $W = V$
- With SVD, $\tilde{X} = U\Sigma V^T$, the columns of V are the orthonormal eigenvectors of $\tilde{X}^T \tilde{X}$

$$\tilde{X}^T \tilde{X} = V \Sigma^T U^T U \Sigma V^T$$

$$\tilde{X}^T \tilde{X} = V \Sigma^T \Sigma V^T \quad (V^T = V^{-1})$$

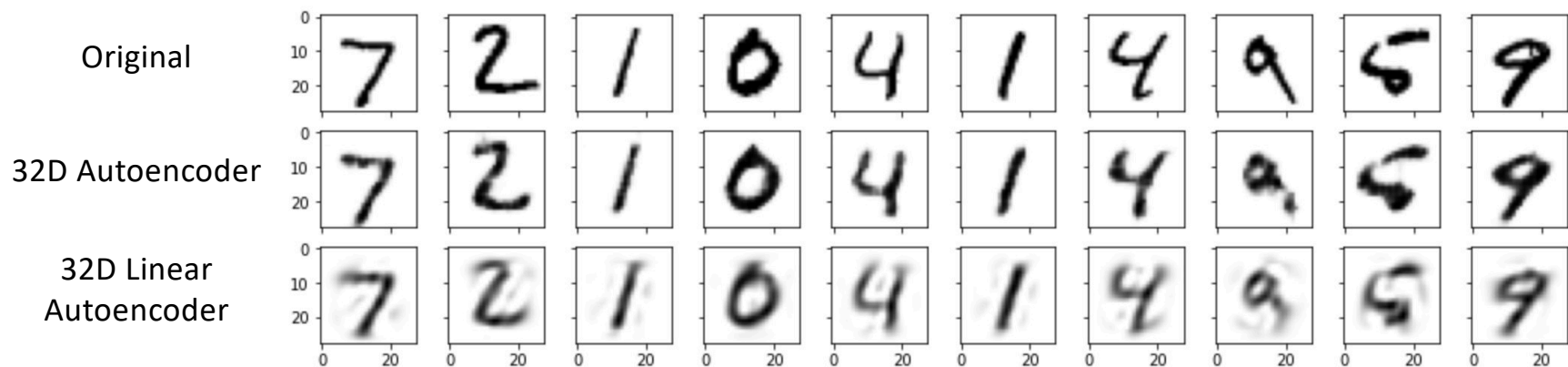
$$\tilde{X}^T \tilde{X} V = V(\Sigma^T \Sigma)$$

Link Between PCA and Autoencoder

- We have encoder $W = V$
- With SVD, $\tilde{X} = U\Sigma V^T$, the columns of V are the orthonormal eigenvectors of $\tilde{X}^T \tilde{X}$
- From PCA, we know that the projection matrix is the matrix of eigenvectors of the **covariance matrix**
- Since the entries of X are normalized by $\tilde{x}_{ij} = \frac{1}{\sqrt{m}}\left(x_{ij} - \frac{1}{m}\sum_{k=1}^m x_{kj}\right)$, $\tilde{X}^T \tilde{X}$ is the covariance matrix
- Thus, the linear encoder W and the projection matrix for PCA could be the same

Link Between PCA and Autoencoder

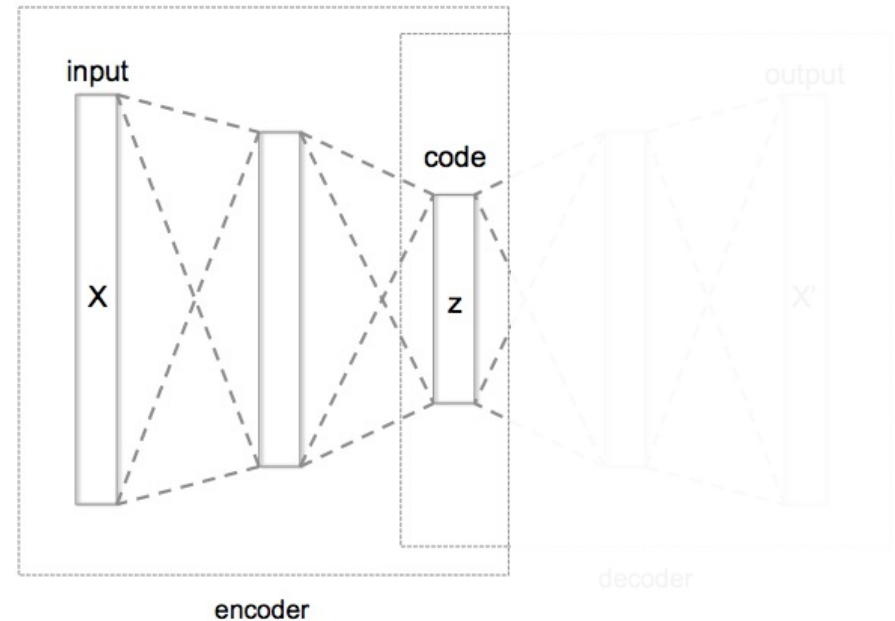
- Nonlinear autoencoder can learn more powerful codes for a given dimensionality (e.g., 32), compared with linear autoencoder (PCA)



Autoencoder Applications

- Using the hidden representation as the input to classic machine learning methods e.g., SVM, KNN
- The latent space can be used for visualization (e.g., clustering)
- Anomaly detection

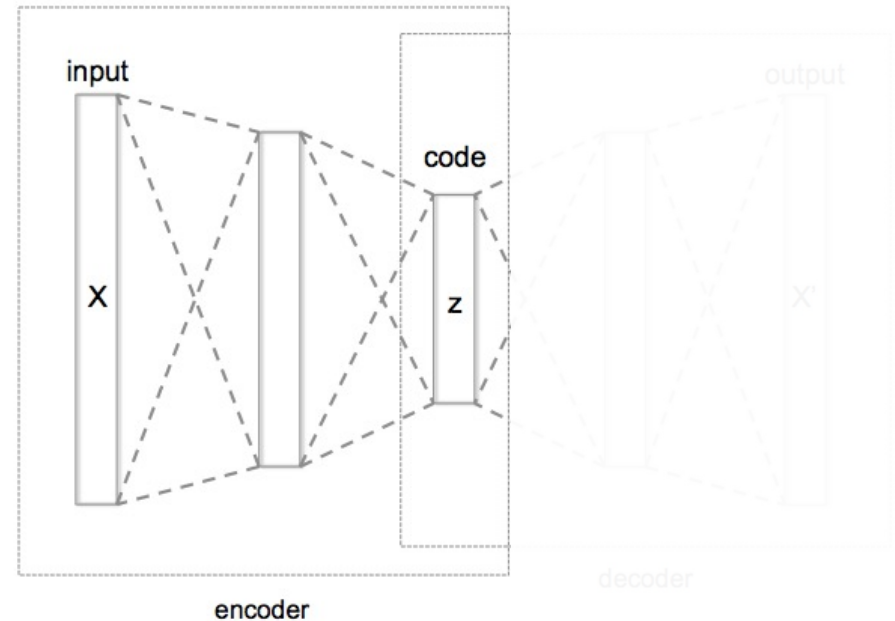
After training, disregarding the decoder



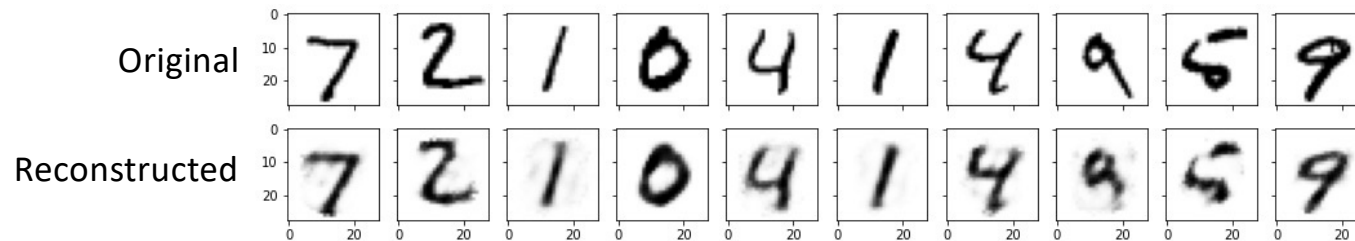
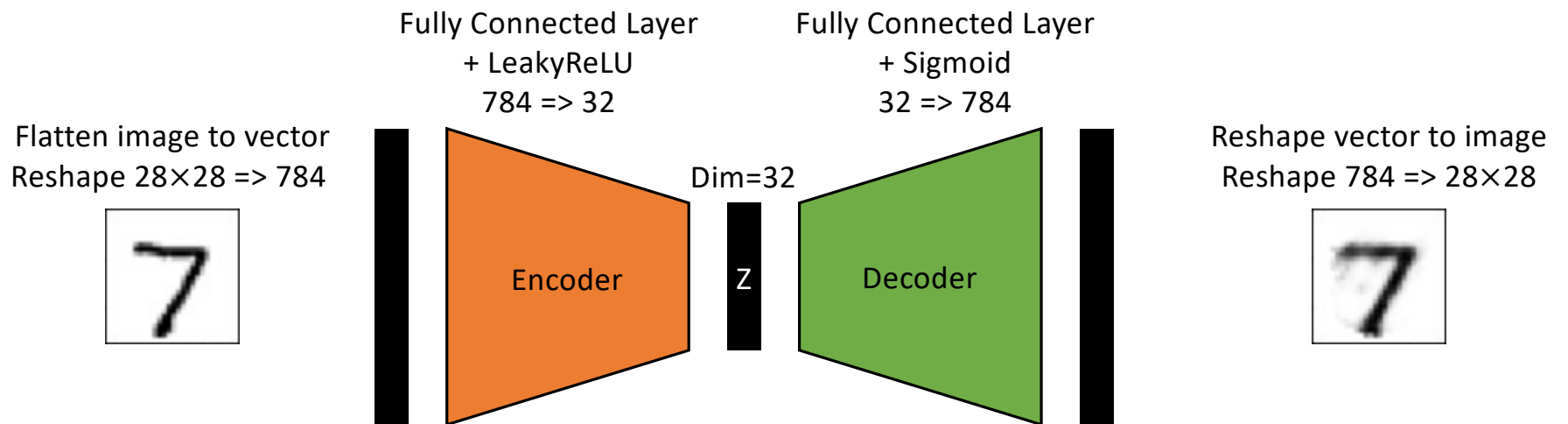
Autoencoder Applications

- Training an autoencoder on a large dataset, then fine tune the encoder part on your own smaller dataset and/or provide your own output layers (e.g., classification)

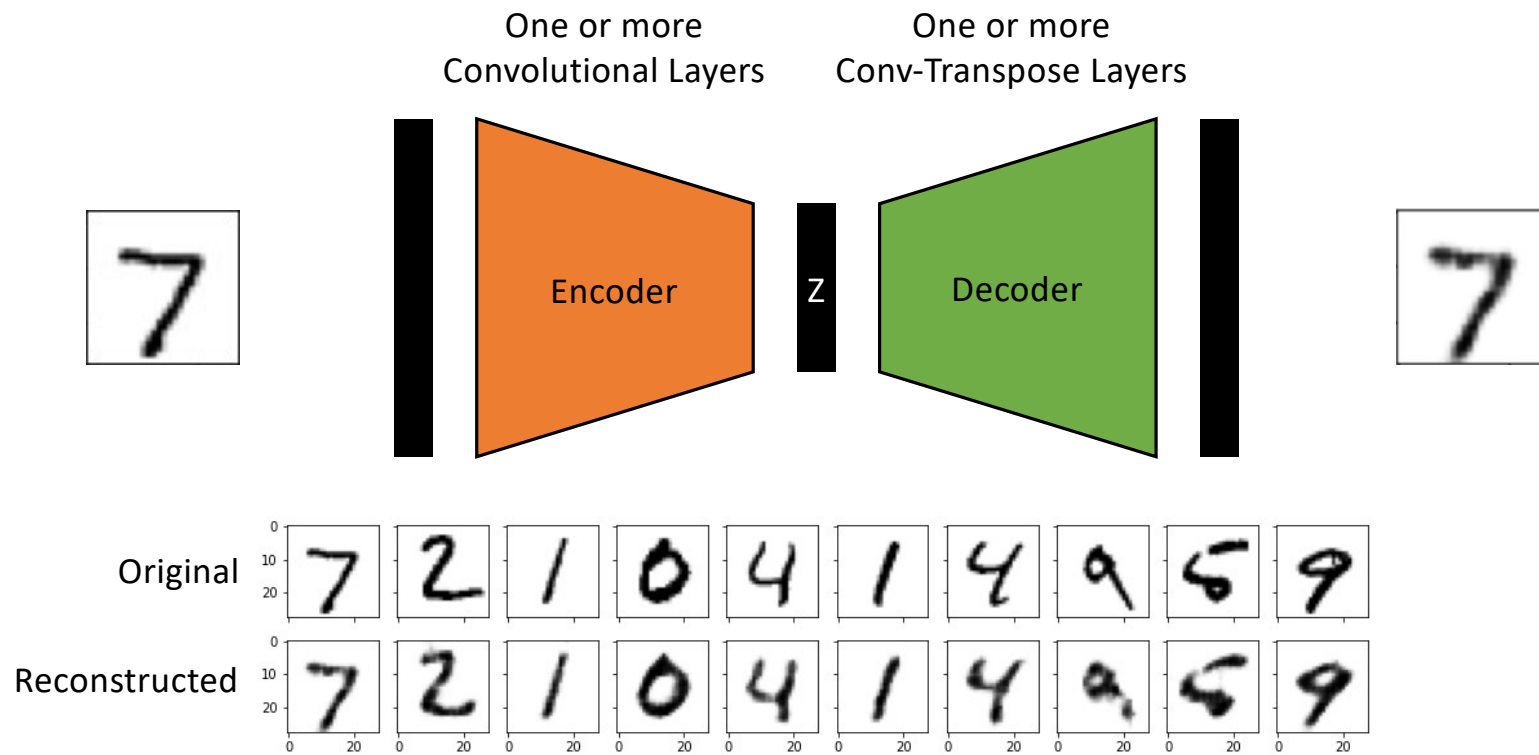
After training, disregarding the decoder



A Fully-Connected Autoencoder on Images

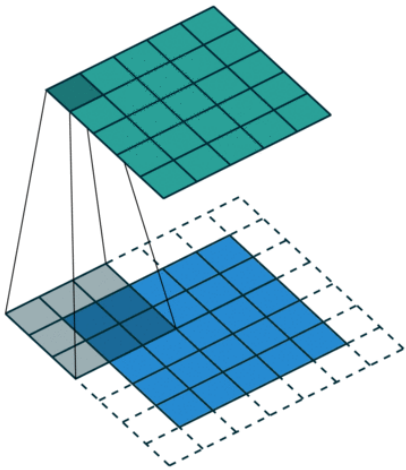


A Convolutional Autoencoder on Images



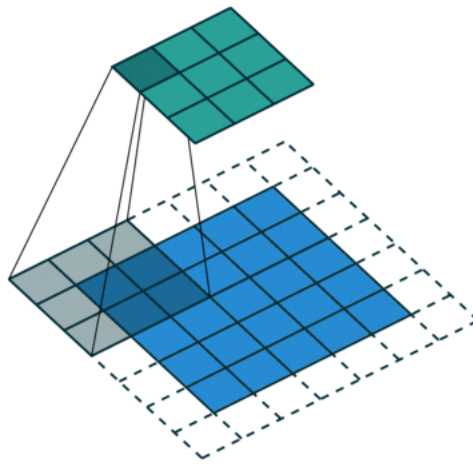
Regular and Transposed Convolution

Regular Convolution
filter size = 3×3
padding = 1
stride = 1



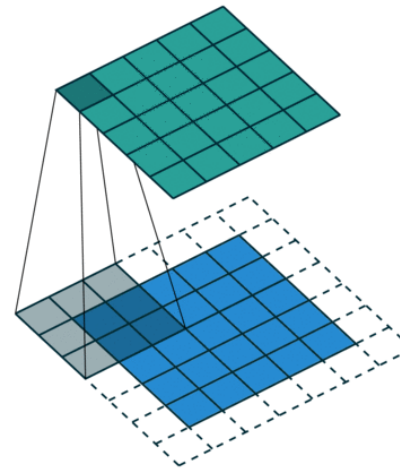
input image size = 5×5
output image size = 5×5

Regular Convolution
filter size = 3×3
padding = 1
stride = 2



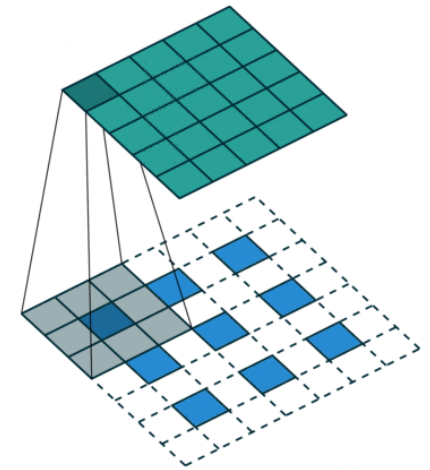
input image size = 5×5
output image size = 3×3

Transposed Convolution
filter size = 3×3
padding = 1
stride = 1



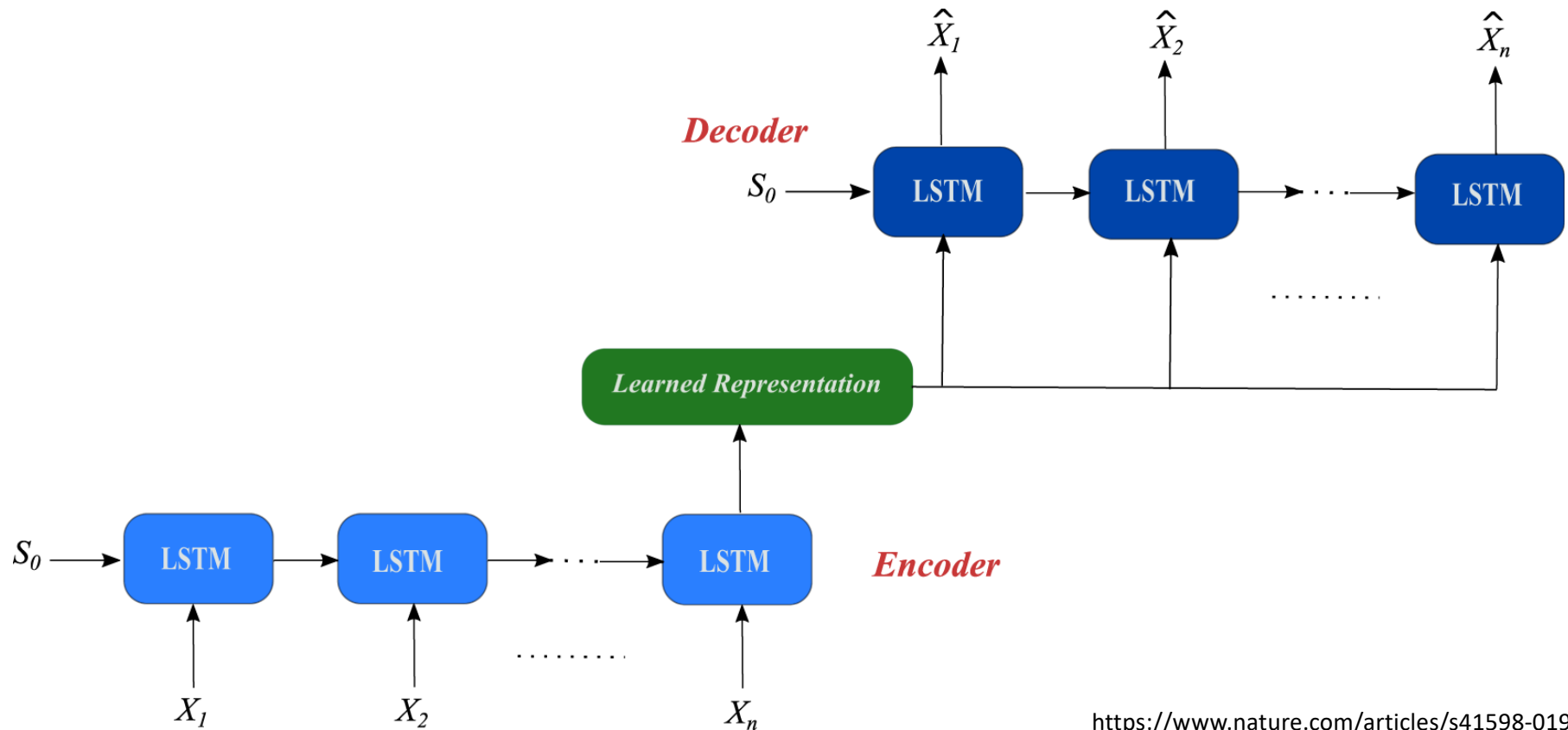
input image size = 5×5
output image size = 5×5

Transposed Convolution
filter size = 3×3
padding = 1
stride = 2



input image size = 3×3
output image size = 5×5

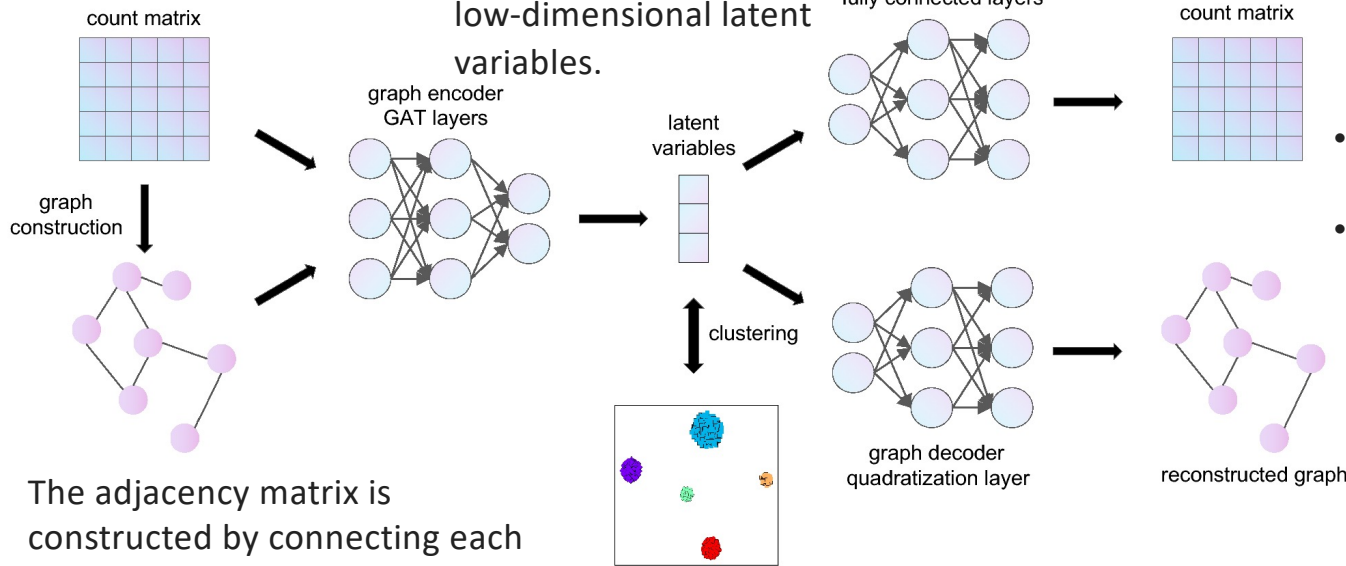
RNN Autoencoder for Sequence Data



GCN Autoencoder for Graph

- The normalized count matrix represents the gene expression level in each cell.

- The encoder takes the count matrix and the adjacency matrix as inputs and generates low-dimensional latent variables.



- The adjacency matrix is constructed by connecting each cell to its K nearest neighbors.

- The feature decoder reconstructs the count matrix.
- The graph decoder reconstructs the adjacency matrix.

- Clustering is performed on the latent variables.

Regularized Autoencoder

- Autoencoders are trained to preserve as much information as possible of the input data with smaller vectors

Regularized Autoencoder

- Autoencoders are trained to preserve as much information as possible of the input data with smaller vectors
- Moreover, autoencoders are to create **meaningful representations** of the input
 - More neurons (i.e., hidden size) than the input size allow the network to compute powerful representations of the input

Regularized Autoencoder

- However, when the hidden dimension is higher than the input
 - No compression needed, also called **overcomplete AE**
 - The network trivially **learns to just copy**, not learning meaningful features

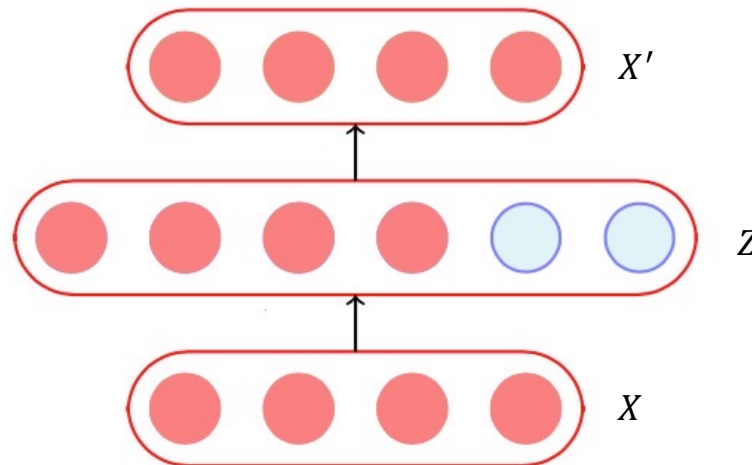


Image by Mitesh M. Khapra

Regularized Autoencoder

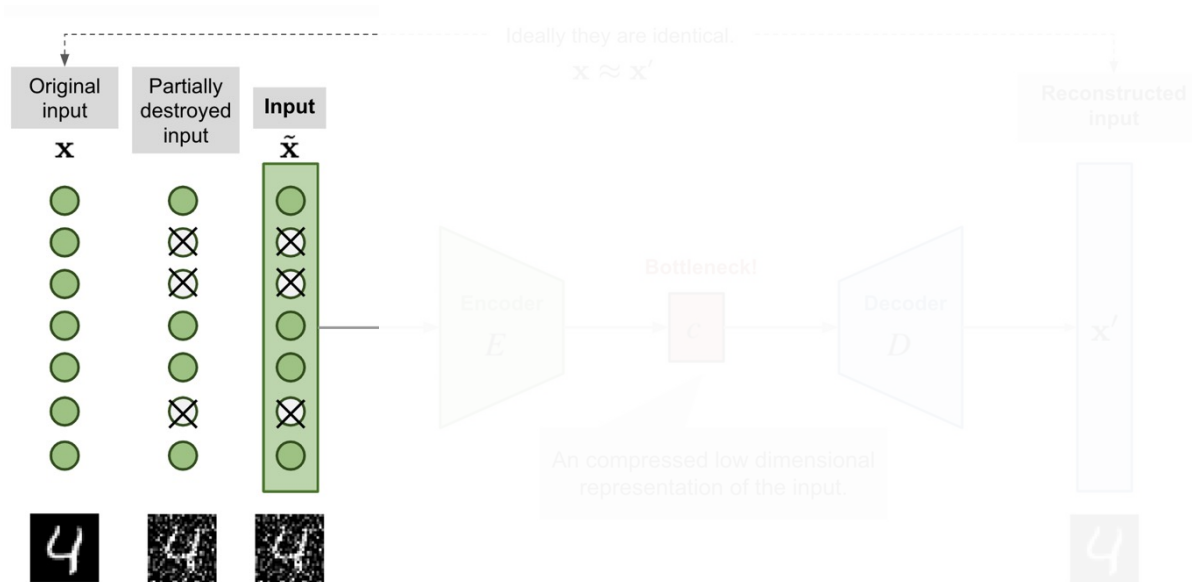
- Regularized autoencoders aim to avoid overfitting and improve robustness
 - Denoise Autoencoder [1]
 - Sparse Autoencoder [2]

[1] Pascal Vincent, et al. ["Stacked denoising autoencoders: Learning useful representations in a deep network with a local denoising criterion."](#)
Journal of machine learning research 11.Dec (2010): 3371-3408.

[2] Ng, Andrew. "Sparse autoencoder." CS294A Lecture notes 72.2011 (2011): 1-19.

Denoise Autoencoder

- The input is partially corrupted by adding noises to or masking some values of the input vector in a stochastic manner

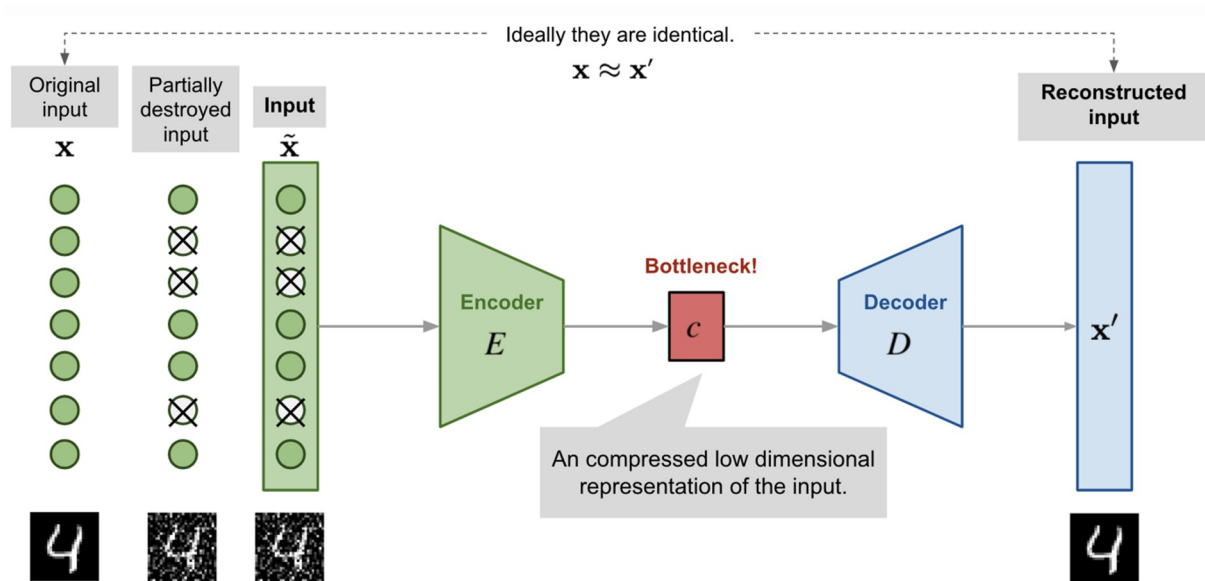


$$\tilde{x}^{(i)} \sim \mathcal{M}_D(\tilde{x}^{(i)} | x^{(i)})$$

where \mathcal{M}_D defines the mapping from the true data samples to the noisy or corrupted ones, e.g., masking noise, Gaussian noise

Denoise Autoencoder

- Then the model is trained to recover the original input (note: not the corrupt one)



$$\min_{\theta, \phi} \frac{1}{n} \sum_{i=1}^n (x^{(i)} - f_{\theta}(g_{\phi}(\tilde{x}^{(i)})))^2$$

[Denoising AE architecture](#) by [Lilian Weng](#)

Denoise Autoencoder – Experiment Results

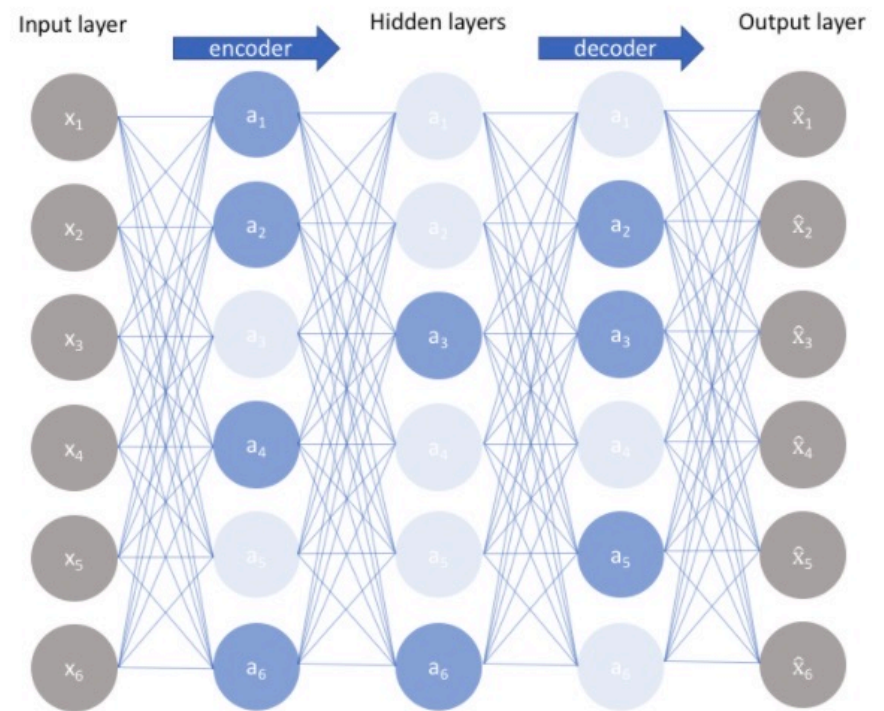
- The model **learns a combination of many input dimensions** to recover the denoised version rather than to overfit one dimension, which helps learn robust latent representation



Original input, corrupted data, and reconstructed data. Copyright by opendeep.org.

Sparse Autoencoder

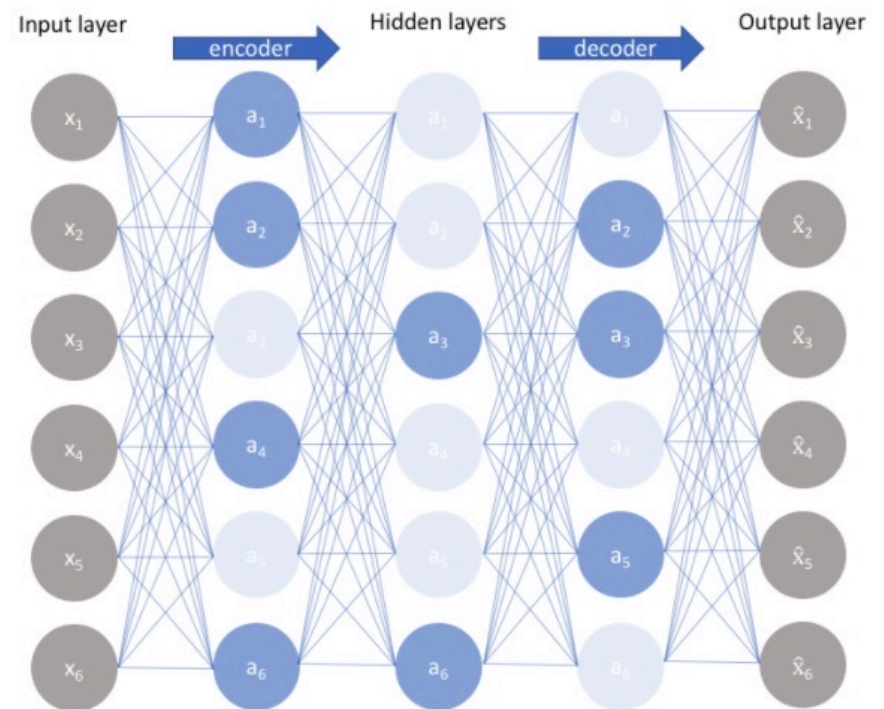
- Sparse autoencoder forces the model to only have a small number of hidden units being activated at the same time



Sparse Autoencoder image by [Syoya Zhou](#)

Sparse Autoencoder

- Sparse autoencoder forces the model to only have a small number of hidden units being activated at the same time
- Loss = reconstruction loss + regularization loss
- There are two ways to construct sparsity penalty
 - L1 regularization
 - KL-divergence



Sparse Autoencoder image by [Syoya Zhou](#)

Sparse Autoencoder with KL-divergence

- Let's say there are s_l neurons in the l^{th} hidden layer and the activation function for the j^{th} neuron in this layer is labelled as $a_j^{(l)}(.)$

Sparse Autoencoder with KL-divergence

- Let's say there are s_l neurons in the l^{th} hidden layer and the activation function for the j^{th} neuron in this layer is labelled as $a_j^{(l)}(.)$
- The average activation of neuron $\hat{\rho}_j$ is expected to be a small number ρ , known as *sparsity parameters*

$$\hat{\rho}_j^{(l)} = \frac{1}{n} \sum_{i=1}^n [a_j^{(l)}(x^{(i)})] \approx \rho$$

- $[a_j^{(l)}(x^{(i)})] = 1$ • if the neuron is activated (e.g., has a value >0.5), 0 otherwise
- n is the number of input sample

Sparse Autoencoder with KL-divergence

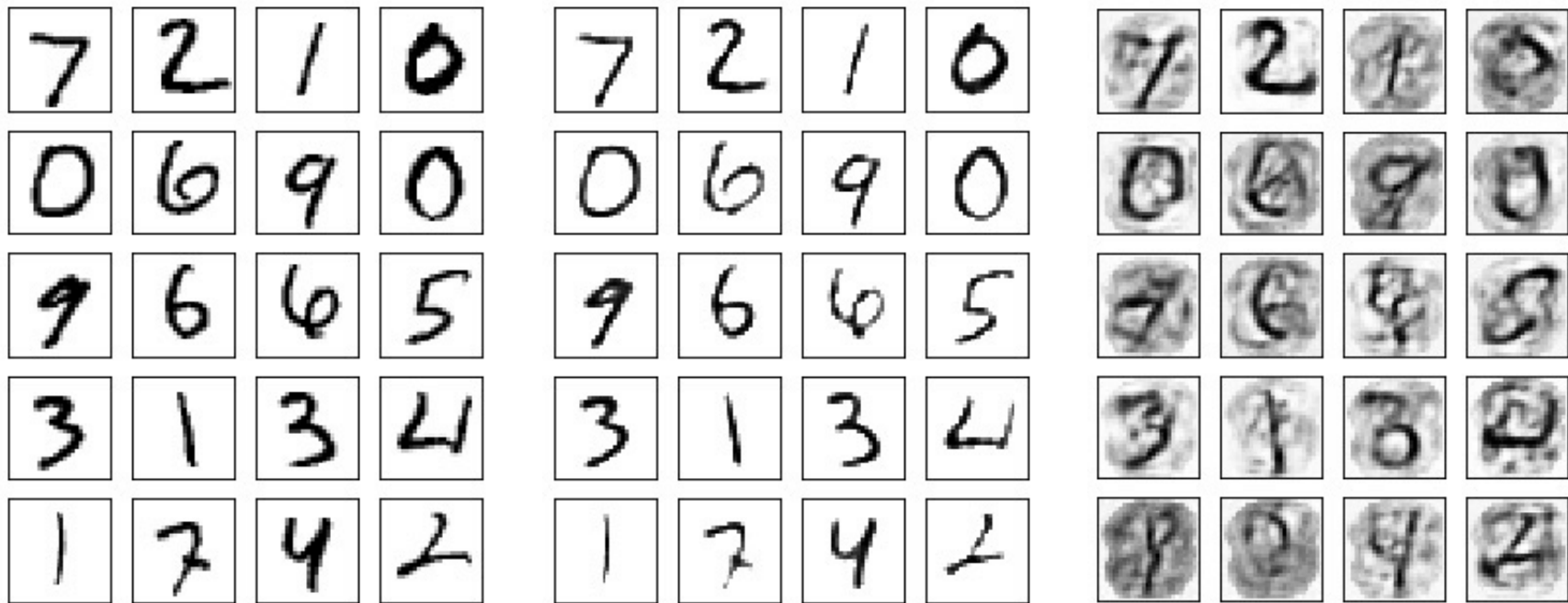
- The KL-divergence measures the difference between two probability distributions,¹ one with mean ρ and the other with mean $\rho_j^{(l)}$

$$L_{SAE} = L_{MSE} + \beta \sum_{l=1}^L \sum_{j=1}^{s_l} D_{KL}(\rho \parallel \hat{\rho}_j^{(l)})$$

- The hyperparameter β controls how strong the penalty applying on the sparsity loss

1. The probability distribution here can be viewed as Bernoulli distribution, the discrete probability distribution of a random variable which takes the value 1 with probability p and the value 0 with probability q = p -1: https://en.wikipedia.org/wiki/Bernoulli_distribution

Sparse Autoencoder – Experiment Results



Original input

Reconstructed data

Reconstructed from latent space with zeroed "inactive" neurons (activation < 0.5)

Other Autoencoders

- Variational Autoencoder (VAE)
- Beta-VAE

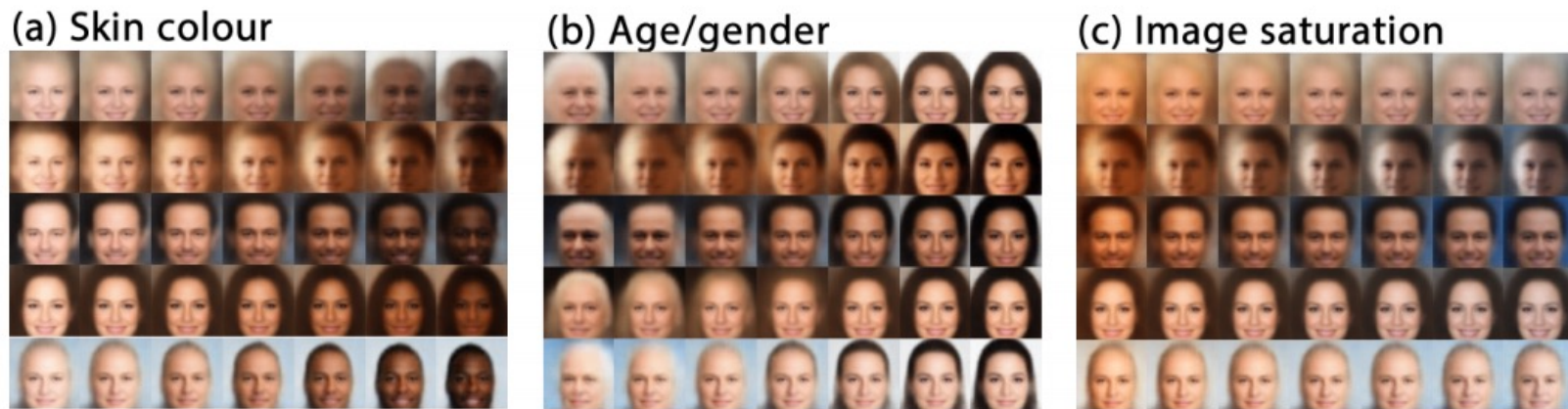


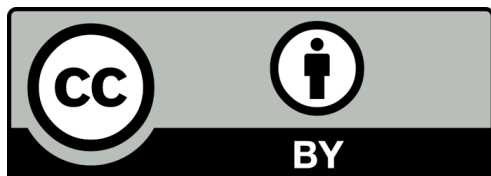
Figure 4: **Latent factors learnt by β -VAE on celebA:** traversal of individual latents demonstrates that β -VAE discovered in an unsupervised manner factors that encode skin colour, transition from an elderly male to younger female, and image saturation.

Autoencoder Summary

- Autoencoder is a neural network architecture designed to learn an identity function in **an unsupervised way** to reconstruct the original input
- Autoencoders can compress the data in a **non-linear way**
- Autoencoders create **meaningful representations** of the input
- Autoencoders with regularization strategy **overcome overfitting and improve the robustness** when there are more neurons in the network than the input
- Many different types of autoencoder structures exist to accommodate various data representations

Acknowledgements

- Deep learning slides adapted from <https://m2dsupsdclass.github.io/lectures-labs/> by Olivier Grisel and Charles Ollion (CC-By 4.0 license)
- Gil, Yolanda (Ed.) Introduction to Computational Thinking and Data Science. Available from <http://www.datascience4all.org>
- <https://lilianweng.github.io/posts/2018-08-12-vae/>



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